



### Pancake Motor Range



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Printed Motor Works are a UK manufacturer of compact electric motors and motor gearboxes providing complete solutions for motion control applications. The company is focused on two strategic areas:

#### **Pancake Motors**

Founded in 1963, we are Europe's largest manufacturer of flat brushed DC pancake electric motors and motor gearboxes. As the world's leading authority on the design and manufacture of pancake motors we continue to explore new areas of application for this unique motor design.

#### **Compact BLDC Motors**

We are considered a world leader in the design and manufacture of compact brushless DC electric motors for the industrial, aerospace & defence, medical, marine and other specialist markets. Our experience spans from compact motors for operating door systems to in-wheel motors for large commercial vehicles.

We have an active policy of total quality control and management throughout the company. We are ISO 9001:2008 certified by BSI British Standards.

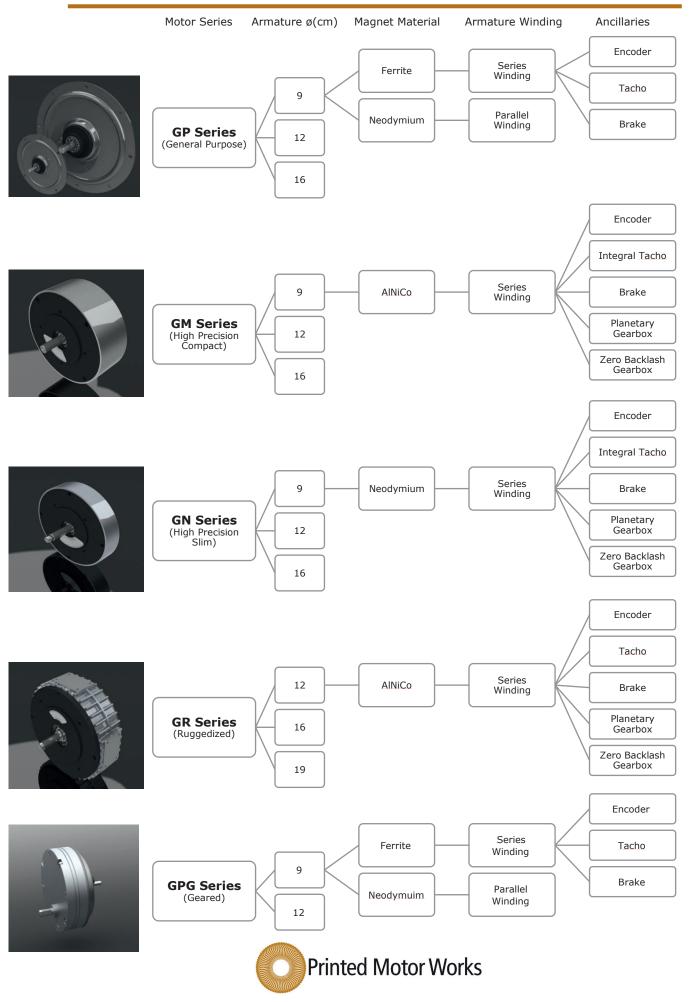
Printed Motor Works is a name that is synonymous with quality products, proven reliability and superior performance.



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# Pancake Motor Guide



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Peak Torque 100 to 1700Ncm
Cont. Torque 10 to 170 Ncm
Power 38 to 533 Watts
Speed 1 to 6000rpm

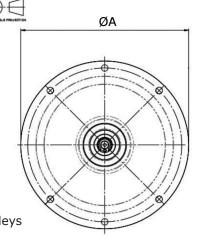
The Printed Motor Works GP series is a totally enclosed DC motor in an ultra slim pancake profile. Incorporating flat armature technology, these pancake motors can provide a cost effective servo capability and are ideal for general purpose applications. Two variants of magnet are available for 9cm, 12cm, and 16cm armature diameters: standard ferrite (GPM) and high-power neodymium magnets (GPN). There are also two variants of armature winding for each size: a parallel low resistance (LR) winding which offers more speed, and a standard series winding which offers more torque.

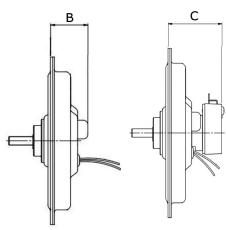


Motor	Power	Torque	Speed	Voltage	Current	Cont. Stall Current	Diameter	Depth	Depth + Encoder
	Р	T	N	V	I	IS	Α	В	C
	Watt	Ncm	RPM	Volt	Amp	Amp	mm	mm	mm
<i>GP</i> M9LR	39	10	3705	9.0	11.7	6.6	120	26.0	44.0
GPM9	41	13	3000	14.5	6.9	4.5	120	26.0	44.0
<i>GP</i> N9LR	75	25	2887	12.0	11.4	6.5	120	26.0	44.0
GPN9	94	30	3000	22.5	6.9	4.5	120	26.0	44.0
<i>GP</i> M12LR	64	20	3050	12.0	10.8	6.5	152	30.0	46.0
GPM12	110	35	3000	23.5	7.6	5.0	152	30.0	46.0
<i>GP</i> N12LR	190	48	3810	24.0	11.0	7.0	152	30.0	46.0
GPN12	200	64	3000	37.5	7.3	5.0	153	30.0	46.0
<i>GP</i> M16LR	221	73	2905	24.0	13.4	8.0	215	35.6	51.6
GPM16	300	96	3000	43.3	9.3	6.0	215	35.6	51.6
<i>GP</i> N16LR	324	100	3102	36.0	11.7	8.0	215	35.6	51.6
GPN16	553	170	3000	75.8	8.4	5.7	215	35.6	51.6

#### **Specific benefits**

- Low profile
- · Zero cogging
- Rapid acceleration
- Low inertia
- High instantaneous torque
- High peak torque
- No torque drop-off at speed
- Ultra slow creep capability
- Wide speed range
- Low inductance
- · Long brush life
- Design options include custom shaft, encoders, gearboxes and pulleys
- Available as an open motor for full application integration





Standard Motor

**Encoder Option** 



#### **Applications**

Servo mechanisms, motion control, industrial robots, CNC machining, printing machinery, centrifuges, logistics solutions, medical mobility, medical scanners, flight simulators, marine autopilots and high ambient temperature ventilation.

#### **Markets**

Industrial automation, automotive, medical, life sciences, aerospace & defence, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

#### **Design Modifications**

- Encoders
- Timing pulleys
- Long leads
- Tri-rated cable
- Open/kit option

- Customised shafts
- EMC suppression
- Connectors
- Rated for operation in 150°C ambient
- Mounting customisation

#### **Standard Encoder Options**

Motor	Counts per Rev.	Channels	Type	Supply Voltage
	CPR			V
GPM9	500	A + B + Index	Optical	+ 5
GPN9	500	A + B + Index	Optical	+ 5
GPM12	500	A + B + Index	Optical	+ 5
GPN12	500	A + B + Index	Optical	+ 5
GPM16	500	A + B + Index	Optical	+ 5
GPN16	500	A + B + Index	Optical	+ 5

Note: Standard Option also applies to LR versions. Other resolutions and differential/line driver output versions available on request.

#### **Suggested Drives**

PWM24/10 PWM24/25



Basic motor speed control

6-30Vdc for basic speed control applications. 10Amp and 25Amp with single and twin axis control.

JUNUS



General speed control applications

20-180Vdc for velocity and torque control with 6 digital I/O. 5Amp - 30Amp variants, RS232 communication.

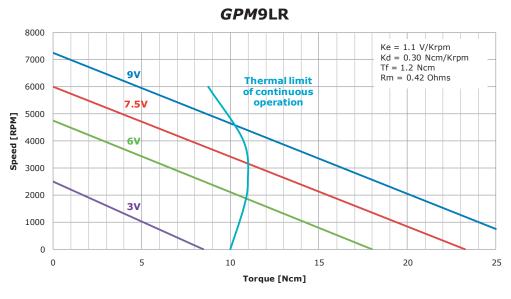
**ACCELNET** 

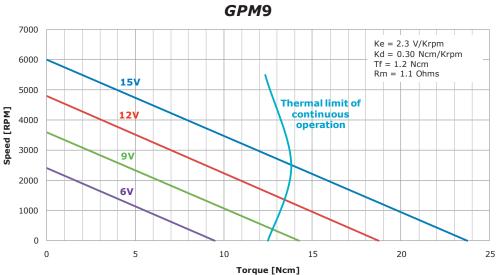


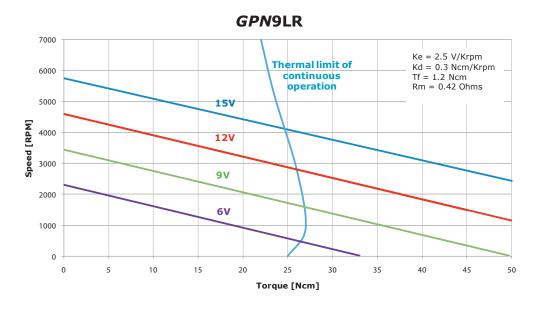
General servo applications

20-180Vdc for velocity, torque and position control with 11 digital I/O and encoder feedback. 5Amp - 36Amp variants, RS232 and macro communication.







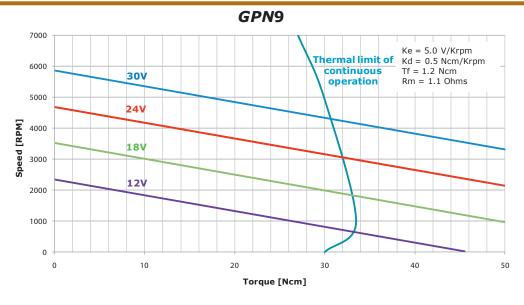


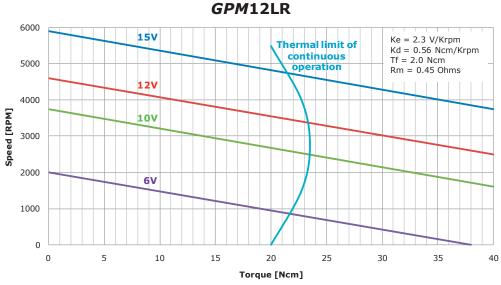
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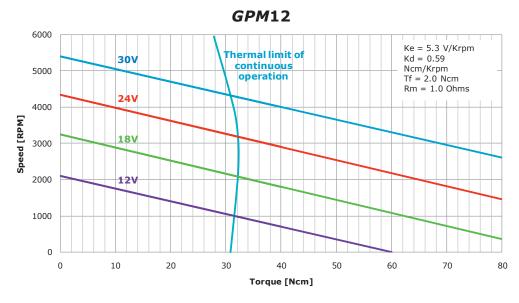


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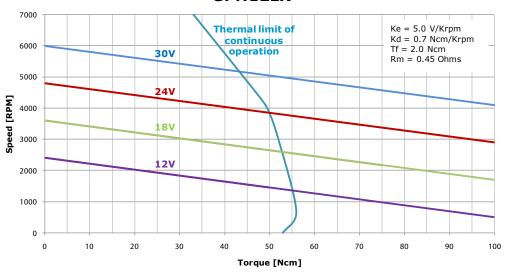
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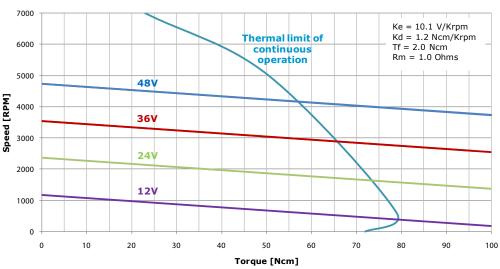
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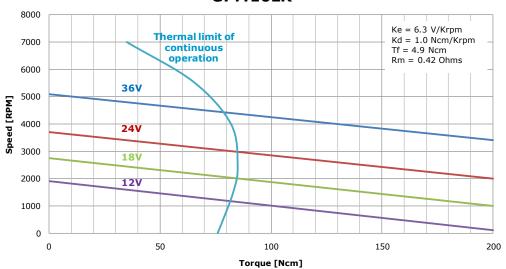




### GPN12



### **GPM16LR**

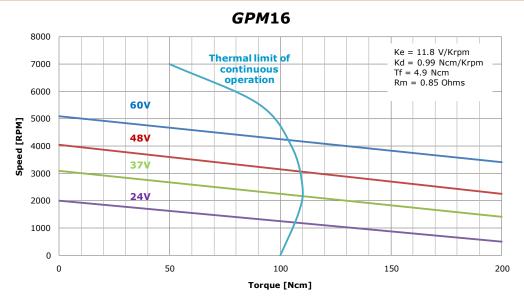


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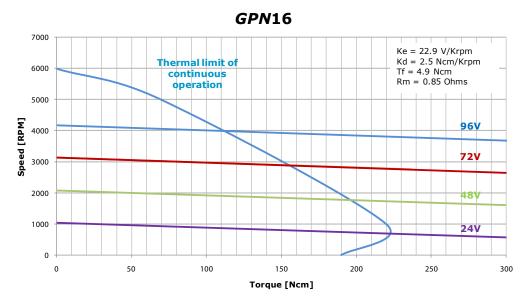


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#### **GPN16LR** Ke = 10 V/Krpm Kd = 2.5 Ncm/Krpm Tf = 4.9 Ncm Thermal limit of 6000 continuous Rm = 0.425 Ohmsoperation 5000 48V Speed [RPM] 4000 24V 2000 1000 0 50 100 150 200 250 300 Torque [Ncm]



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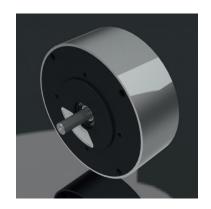


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Peak Torque 360 to 3200 Ncm
Cont. Torque 36 to 320 Ncm
Power 113 to 1000 Watts
Speed <1 to 6000 rpm

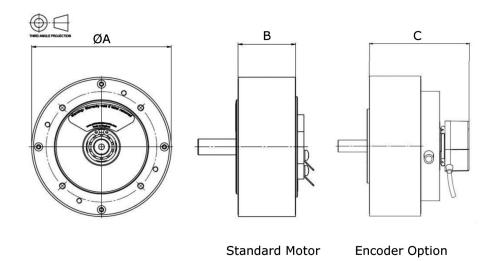
The Printed Motor Works GM series is the original printed armature motor. Extremely powerful and accurate, the GM range brings all the benefits of printed armature technology to industrial applications. Higher torque 'H' versions offer more torque for the same package and weight. Low voltage versions are available for vehicle applications (details on application). The GM range is available with a host of options such as: encoders, imperial mounting, adaptors, gearboxes, tachos, resolvers and with custom mounting plates & shafts.



Motor	Power	Torque	Speed	Voltage	Current	Cont. Stall Current	Diameter	Depth	Depth + Encoder
	Р	Т	N	V	I	IS	Α	В	С
	Watt	Ncm	RPM	Volt	Amp	Amp	mm	mm	mm
GM9	113	36	3000	24.1	8.7	6.8	111	46.0	88.5
<i>GM</i> 9H	179	57	3000	31.9	8.6	6.8	111	57.0	99.5
GM12	284	91	3000	43.4	8.8	8.1	142	52.5	101.5
GM12H	396	126	3000	62.7	7.9	8.1	142	70.0	119.0
<i>GM</i> 16	704	227	3000	82.7	11.0	9.2	187.2	61.0	110.0
<i>GM</i> 16H	890	284	3000	125.7	8.5	9.8	187.2	73.0	122.0

#### **Specific benefits**

- High peak torque output
- Zero cogging
- Low inertia
- · Rapid acceleration
- Stable up to high temperatures
- High instantaneous torque
- Long brush life
- Controllable with servo amplifiers
- Design options include custom shaft, encoders, tachometers, gearboxes and pulleys





#### **Applications**

Servo mechanisms, motion control, industrial robots, CNC machining, printing machinery, logistics solutions, medical mobility, medical scanners, flight simulators, marine autopilots and high ambient temperature ventilation, valve actuators and scientific instrumentation.

#### **Markets**

Industrial automation, medical, life sciences, aerospace & defence, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

#### **Design Modifications**

- Encoders
- Timing pulleys
- · Long leads
- Tri-rated cable
- US mounting configuration
- · Customised shafts
- EMC suppression
- Connectors
- Rated for operation in 150°C ambient

#### **Standard Encoder Options**

Motor	Counts per Rev. CPR	Channels	Туре	Supply Voltage V
GM9	5000	A + B + I + Complementary	Optical	+ 5 - 24
GM9H	5000	A + B + I + Complementary	Optical	+ 5 - 24
<i>G</i> M12	5000	A + B + I + Complementary	Optical	+ 5 - 24
GM12H	5000	A + B + I + Complementary	Optical	+ 5 - 24
<i>G</i> M16	5000	A + B + I + Complementary	Optical	+ 5 - 24
GM16H	5000	A + B + I + Complementary	Optical	+ 5 - 24

#### **Suggested Drives**

JUNUS



General speed control applications 20-180Vdc for velocity and torque control with 6 digital I/O. 5Amp - 30Amp variants, RS232 communication.





General servo applications

20-180Vdc for velocity, torque and position control with 11 digital I/O and encoder feedback. 5Amp - 36Amp variants, RS232 and macro communication.

### XENUS



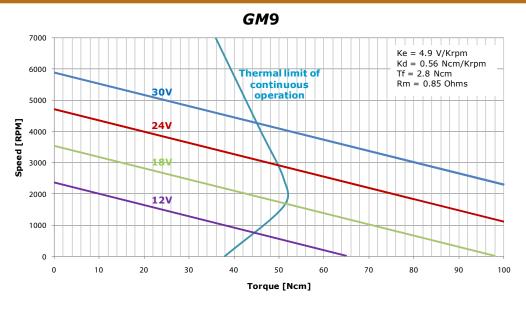
Advanced servo control

110-230Vac for camming, gearing, position, velocity and torque control with 16 digital I/O and multiple feedback options. A stand alone motion control device with CANopen and RS232 communication protocols.



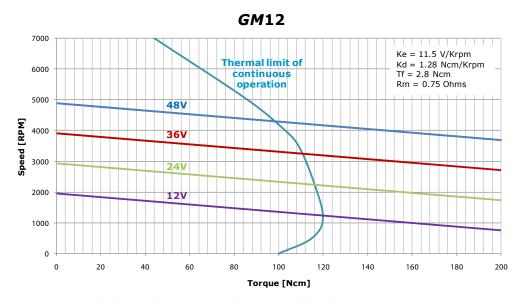
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#### GM9H 7000 Ke = 8.8 V/Krpm Kd = 0.71 Ncm/KrpmThermal limit of 6000 Tf = 2.8 Ncmcontinuous Rm = 0.85 Ohmsoperation 48V 5000 Speed [RPM] 24V 2000 12V 1000 0 0 20 40 60 80 100 120 140 160 180 200

Torque [Ncm]

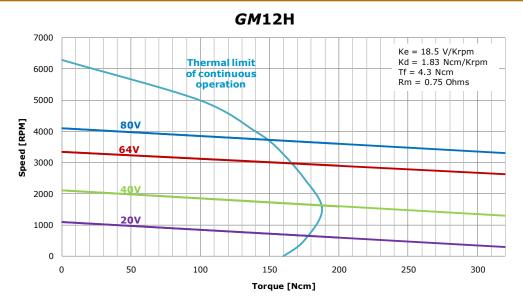


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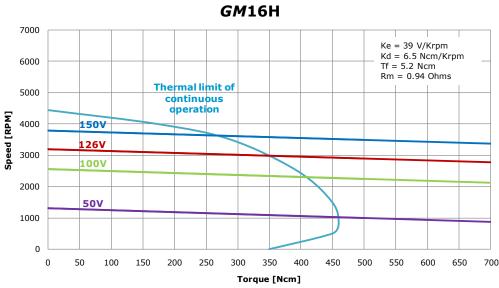


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#### **GM16** 7000 Ke = 23 V/Krpm Kd = 4.2 Ncm/Krpm Tf = 5 Ncm Rm = 0.94 Ohms Thermal limit of 6000 continuous operation 120V 5000 Speed [RPM] 4000 80V 3000 60V 2000 20V 1000 0 0 50 100 150 200 250 300 350 400 450 500 Torque [Ncm]



NOTE: The above voltages are examples, not a predefined maximum or minimum. Due to ongoing product improvements data is subject to change without notice.



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### **GN** Series

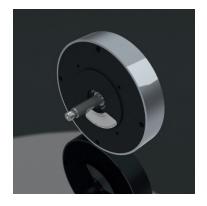
 Peak Torque
 490 to 2550 Ncm

 Cont. Torque
 49 to 255 Ncm

 Power
 140 to 800 Watts

 Speed
 <1 to 6000 rpm</td>

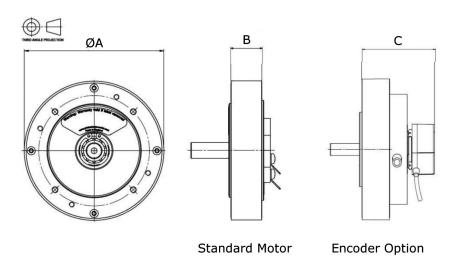
The Printed Motor Works GN series is an exceptionally powerful and extremely accurate range of servo motors that provide all the advantages of the printed armature with the thin profile made possible by using rare earth magnet materials. The GN series is suitable for all types of industrial automation, robotics and scientific applications. GN motors are available in 3 sizes GN9, 12 and 16.



Motor Ratings	Power	Torque	Speed	Voltage	Current	Cont. Stall Current	Diameter	Depth	Depth + Encoder
	Р	Т	N	V	I	IS	Α	В	С
	Watt	Ncm	RPM	Volt	Amp	Amp	mm	mm	mm
GN9	154	49	3000	30	7.8	7.8	110	34.0	50.0
GN12	344	110	3000	49	9.2	8.9	140	25.8	41.8
GN16	800	255	3000	100	9.4	8.0	188	26.0	42.0

#### **Specific benefits**

- · High peak torque output
- · Zero cogging
- Low inertia
- Rapid acceleration
- High instantaneous torque
- Long brush life
- Controllable with servo amplifiers
- Design options include custom shaft, encoders, tachometers, gearboxes and pulleys





### **GN** Series

#### **Applications**

Servo mechanisms, motion control, industrial robots, CNC machining, printing machinery, logistics solutions, medical mobility, medical scanners, flight simulators, marine autopilots and high ambient temperature ventilation, valve actuators and scientific instrumentation.

#### **Markets**

Industrial automation, medical, life sciences, aerospace & defence, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

#### **Design Modifications**

- Encoders
- Timing pulleys
- Long leads
- Tri-rated cable

- Customised shafts
- EMC suppression
- Connectors
- US mounting configuration

#### **Standard Encoder Options**

Motor	Counts per Rev. CPR	Channels	Type	Supply Voltage V
GN9	5000	A + B + I + Complementary	Optical	+ 5 - 24
GN12	5000	A + B + I + Complementary	Optical	+ 5 - 24
GN16	5000	A + B + I + Complementary	Optical	+ 5 - 24

#### **Suggested Drives**

#### JUNUS



General speed control applications
20-180Vdc for velocity and torque control with 6

digital I/O. 5Amp - 30Amp variants, RS232 communication.

#### **ACCELNET**



#### General servo applications

20-180Vdc for velocity, torque and position control with 11 digital I/O and encoder feedback. 5Amp - 36Amp variants, RS232 and macro communication.

#### **XENUS**



#### Advanced servo control

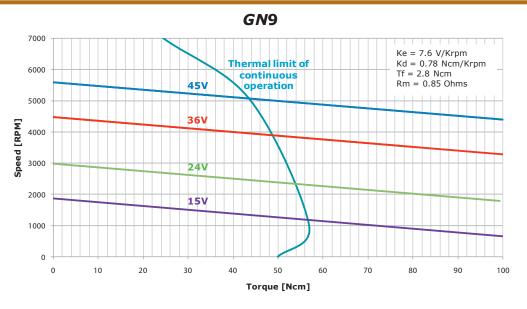
110-230Vac for camming, gearing, position, velocity and torque control with 16 digital I/O and multiple feedback options. A stand alone motion control device with CANopen and RS232 communication protocols.



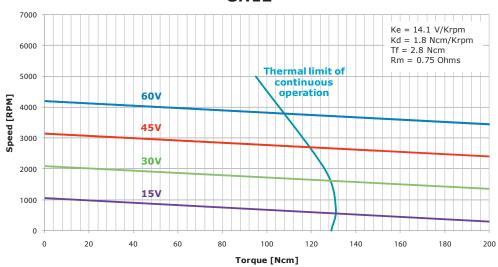
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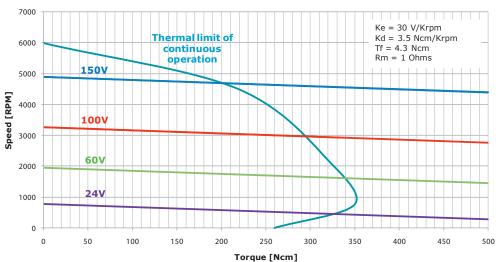
## **GN** Series



### **GN12**



#### **GN16**



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### **GR** Series

Peak Torque 1334 to 3200 Ncm
Cont. Torque 133.4 to 320 Ncm
Power 420 to 1000 Watts
Speed <1 to 6000 rpm

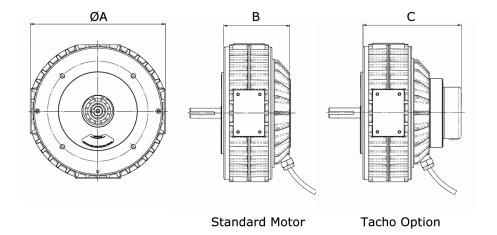
The Printed Motor Works GR series is an exceptionally powerful and extremely accurate range of servo motors that provide all the advantages of the printed armature with an extremely robust motor case for industrial automation and scientific applications. GR motors include air cooling ports, with removable covers, for use with external cooling fans to increase the thermal limit of continuous operation. GR motors are available in 3 sizes GR12, 16 and 19.

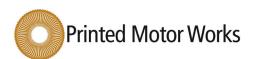


Motor Ratings	Power	Torque	Speed	Voltage	Current	Cont. Stall Current	Diameter	Depth	Depth + Tacho
	Р	Т	N	V	I	IS	Α	В	С
	Watt	Ncm	RPM	Volt	Amp	Amp	mm	mm	mm
GR12	420	133	3000	64	8.4	5.0	142	70.0	148
<i>GR</i> 16	1050	334	3000	129	9.5	5.7	187	87.5	159
GR19	1000	320	3000	83	14.5	8.6	230	107.5	157

#### **Specific benefits**

- · High peak torque output
- Zero cogging
- Low inertia
- Rapid acceleration
- Stable up to high temperatures
- High instantaneous torque
- · Long brush life
- Controllable with servo amplifiers
- Design options include custom shaft, encoders, tachometers, gearboxes and pulleys





### **GR** Series

#### **Applications**

Servo mechanisms, motion control, industrial robots, CNC machining, printing machinery, logistics solutions, medical mobility, medical scanners, flight simulators, marine autopilots and high ambient temperature ventilation, valve actuators and scientific instrumentation.

#### Markets

Industrial automation, medical, life sciences, aerospace & defence, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

#### **Design Modifications**

- Encoders
- Timing pulleys
- Tacho output voltage
- Tri-rated cable
- US mounting configuration
- Customised shafts
- EMC suppression
- Connectors
- Rated for operation in 150°C ambient
- Protective covers

### **Standard Tacho Options**

Motor	Output Voltage Gradient	Output Tolerance	Voltage Ripple	Rotor Inertia
	V/KRPM	%	%	g/cm²
GR12	3	+5 -0	5	350
<i>GR</i> 16	3	+5 -0	5	350
<i>GR</i> 19	3	+5 -0	5	350

#### **Suggested Drives**

### JUNUS



General speed control applications
20-180Vdc for velocity and torque control with 6
digital I/O. 5Amp - 30Amp variants, RS232
communication.

#### **ACCELNET**



#### General servo applications

20-180Vdc for velocity, torque and position control with 11 digital I/O and encoder feedback. 5Amp - 36Amp variants, RS232 and macro communication.

#### **XENUS**



#### Advanced servo control

110-230Vac for camming, gearing, position, velocity and torque control with 16 digital I/O and multiple feedback options. A stand alone motion control device with CANopen and RS232 communication protocols.

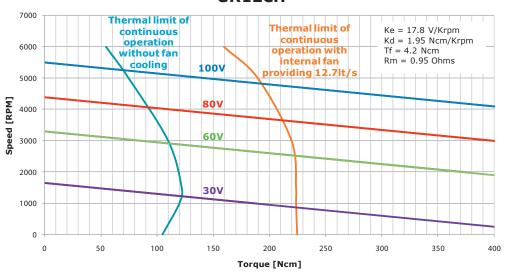


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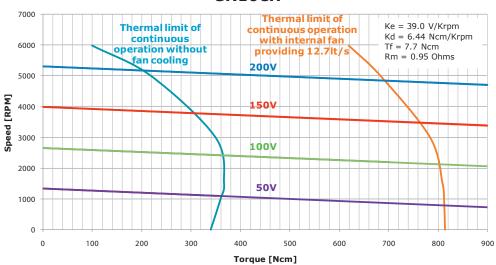
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### **GR** Series

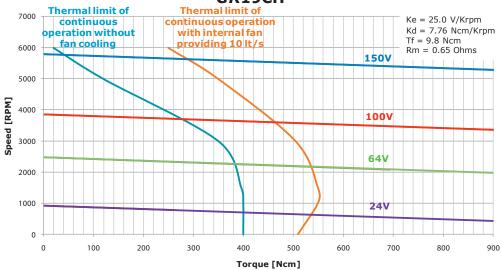
#### GR12CH



#### GR16CH



### GR19CH

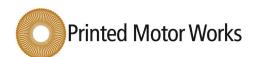


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### GPG9 Series

Torque 39 Nm

Ratios **80:1 to 150:1**Speed **<0.1 to 88 rpm** 

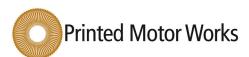
The Printed Motor Works GPG9 series offers a selection of gear reduction ratios for the GP9 motors. These gear motors offer high torque in a compact axial package and use spur gears to reduce speed and efficiently increase the torque of the 9cm pancake motors. Each unit comes with gearbox and motor fully assembled.



Motor	Gear Ratio (value: 1)	150	80
	Continuous (Nm)	17	9
GPG9F	Current (Amp)	6.9	6.9
	Speed (RPM) @ 24v	34	64
	Speed (RPM) @ 12v	27	50
<i>GPG</i> 9N	Continuous (Nm)	39	21
	Current (Amp)	6.9	6.9
	Speed (RPM) @ 36v	31	58
	Speed (RPM) @ 24v	23	44
	Continuous (Nm)	13	7
<i>GPG</i> 9FLR	Current (Amp)	11.7	11.7
GPG9FLK	Speed (RPM) @ 24v	47	88
	Speed (RPM) @ 12v	30	56
	Continuous (Nm)	32	17
<i>GPG</i> 9NLR	Current (Amp)	11.4	11.4
GPOSNER	Speed (RPM) @ 24v	27	50
	Speed (RPM) @ 12v	19	36

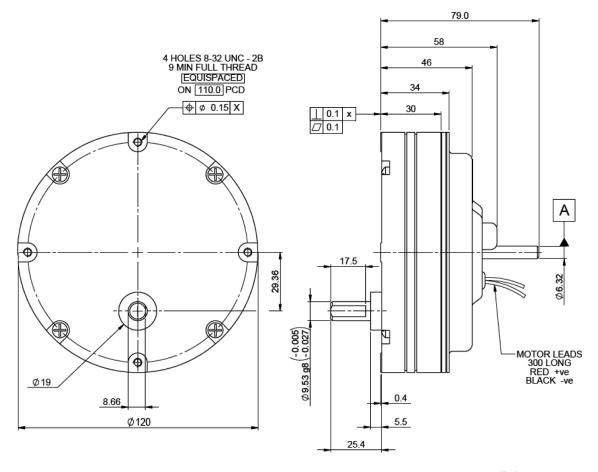
#### **Specific benefits**

- High peak torque output
- Zero cogging
- Low inertia
- Rapid acceleration
- Stable up to high temperatures
- High instantaneous torque
- Long brush life
- Controllable with servo amplifiers
- Design options include custom shaft, encoders and pulleys



## GPG9 Series





All dimensions in mm

#### **Applications**

Biomedical analysis, inspection systems, X-Y tables, wheel drive, automatic door actuators, general automation, advertising screens, weld wire feed, seat elevation adjustment, turret drive.

#### **Markets**

Industrial automation, medical, life sciences, aerospace & defence, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

#### **Design Modifications**

- Encoders
- Timing pulleys
- Tri-rated cable

- Customised shafts
- EMC suppression
- Connectors

#### **Standard Encoder Options**

Mo	tor	Counts per Rev. CPR	Channels	Туре	Supply Voltage V
GP	G9F	500	A + B + Index	Optical	+ 5
GP	G9N	500	A + B + Index	Optical	+ 5
GP	G9FLR	500	A + B + Index	Optical	+ 5
GP	G9NLR	500	A + B + Index	Optical	+ 5



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### GPG9 Series

#### **Suggested Drives**

PWM24/10 PWM24/25

Basic motor speed control 6-30Vdc for basic speed control applications. 10Amp and 25Amp with single and twin axis



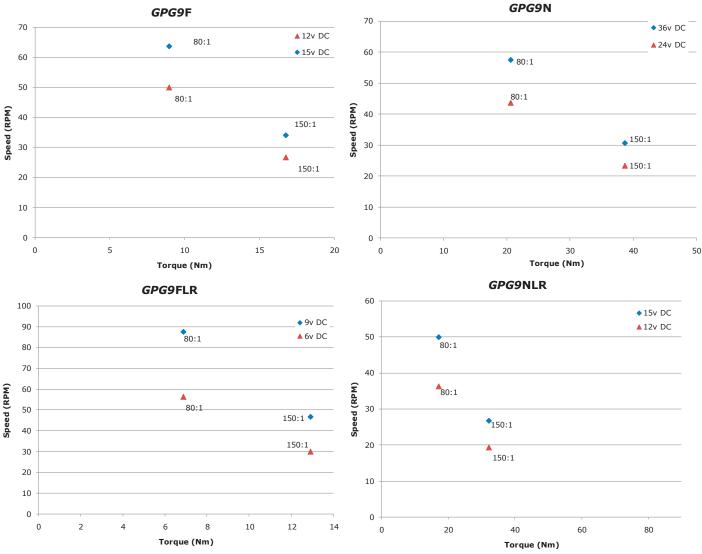
General speed control applications 20-180Vdc for velocity and torque control with 6 digital I/O. 5Amp - 30Amp variants, RS232 communication.



General servo applications

control.

20-180Vdc for velocity, torque and position control with 11 digital I/O and encoder feedback. 5Amp - 36Amp variants, RS232 and macro communication.



NOTE: The above voltages are examples, not a predefined maximum or minimum. Due to ongoing product improvements data is subject to change without notice.





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Peak Torque 17 Nm to 1134 Nm
Cont. Torque 49 to 255 Ncm
Ratios 10:1 to 206:1
Speed <0.1 to 500 rpm

The Printed Motor Works GPG12 series offers a wide range of gear reduction ratios for the GP12 motors. Offering high torque in a compact axial package, each unit has foot mounting capability and uses a combination of bevel and planetary gears to reduce the speed and efficiently increase the torque of the 12cm pancake motor. Each unit comes with gearbox and motor fully assembled.



Motor	Gear Ratio (value : 1)	206	120	80	60	40	25	12	10
	Continuous (Nm)	71	41	28	21	14	9	4	3
CDCM12	Current (Amp)	7.6	7.6	7.6	7.6	7.6	7.6	7.6	7.6
GPGM12	Speed (RPM) @ 24v	15	25	38	50	75	120	250	300
	Speed (RPM) @ 12v	7	13	19	25	38	60	125	150
	Continuous (Nm)	133	77	52	39	26	16	8	6
GPGN12	Current (Amp)	7.3	7.3	7.3	7.3	7.3	7.3	7.3	7.3
GPGN12	Speed (RPM) @ 36v	15	25	38	50	75	120	250	300
	Speed (RPM) @ 24v	10	17	25	33	50	80	167	200
	Continuous (Nm)	35	21	14	10	7	4	2	2
<i>GPG</i> M12LR	Current (Amp)	10.8	10.8	10.8	10.8	10.8	10.8	10.8	10.8
GFGM12LK	Speed (RPM) @ 24v	24	42	63	83	125	200	417	500
	Speed (RPM) @ 12v	12	21	31	42	63	100	208	250
	Continuous (Nm)	87	51	34	25	17	11	5	4
<i>GPG</i> N12LR	Current (Amp)	11.0	11.0	11.0	11.0	11.0	11.0	11.0	11.0
OFGIVIZER	Speed (RPM) @ 24v	17	30	45	60	90	144	300	360
	Speed (RPM) @ 12v	9	15	23	30	45	72	150	180

#### **Specific benefits**

- High peak torque output
- Zero cogging
- Low inertia
- Rapid acceleration
- Stable up to high temperatures
- High instantaneous torque
- Long brush life
- Controllable with servo amplifiers
- Design options include custom shaft, encoders and pulleys



We have two designs for the GPG series depending on the ratio you require.

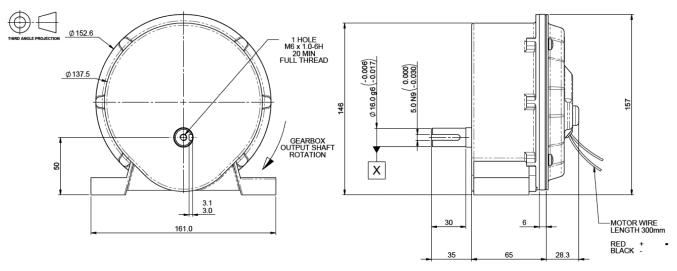
Please see the table below for the various ratios and the corresponding design.

Design A
Design B

12:1, 40:1, 60:1, 80:1, 120:1, 206:1

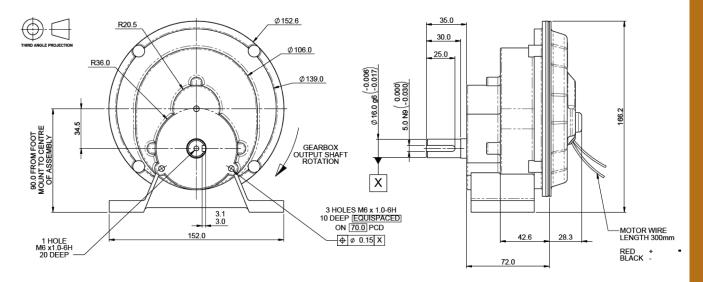
10:1, 25:1

#### Design A

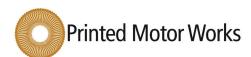


All dimensions in mm

#### Design B



All dimensions in mm



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#### **Applications**

Biomedical analysis, inspection systems, X-Y tables, wheel drive, automatic door actuators, general automation, advertising screens, weld wire feed, seat elevation adjustment, turret drive.

#### **Markets**

Industrial automation, medical, life sciences, aerospace & defence, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

#### **Design Modifications**

- Encoders
- Timing pulleys
- Tri-rated cable

- Customised shafts
- EMC suppression
- Connectors

#### **Standard Encoder Options**

Motor	Counts per Rev.	Channels	Type	Supply Voltage V
GPGM12	500	A + B + Index	Optical	+ 5
GPGN12	500	A + B + Index	Optical	+ 5
GPGM12LR	500	A + B + Index	Optical	+ 5
GPGN12LR	500	A + B + Index	Optical	+ 5

#### **Suggested Drives**

PWM24/10 PWM24/25



Basic motor speed control

6-30Vdc for basic speed control applications. 10Amp and 25Amp with single and twin axis control.





General speed control applications

20-180Vdc for velocity and torque control with 6 digital I/O. 5Amp - 30Amp variants, RS232 communication.

**ACCELNET** 

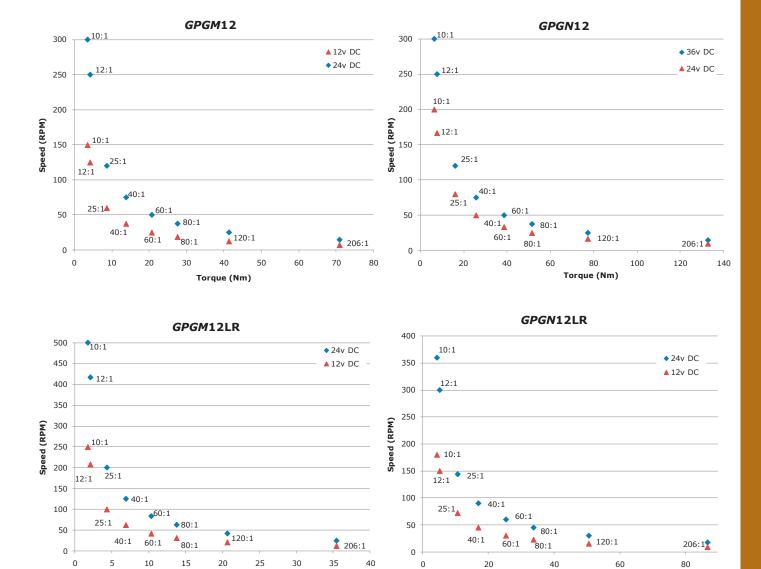


General servo applications

20-180Vdc for velocity, torque and position control with 11 digital I/O and encoder feedback. 5Amp - 36Amp variants, RS232 and macro communication.

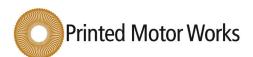


Ratio	Drive train details	Backlash(degrees)	Arc mins	Radial Load (Kg)
206:1	Steel Gear	0.24±0.05°	15.0	230
120:1	Steel Gear	0.49±0.05°	29.4	230
80:1	Steel Gear	0.11±0.05°	6.6	230
60:1	Steel Gear	0.91±0.05°	54.6	230
40:1	Steel Gear	0.45±0.05°	27.0	230
25:1	Steel Gear(Planetary)	0.46±0.05°	27.6	230
12:1	MC Nylon Gear	0.12±0.05°	7.2	230
10:1	MC Nylon Gear(Planetary)	0.46±0.05°	27.6	230



NOTE: The above voltages are examples, not a predefined maximum or minimum. Due to ongoing product improvements data is subject to change without notice.

Torque (Nm)



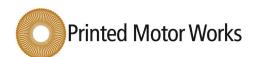
Torque (Nm)

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